

# **MANUAL**

## **INKLINATOR CMI PRODUCTION No boom**

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#### 1 GENERAL DESCRIPTION

The **INKLINATOR** CMI Production is designed to for non boom production drill rigs. The CMI Production no boom is a **modular-built system** showing, controlling and collecting drilling-related information. This improves the quality and accuracy of the drilling operation which in turn improves productivity and working conditions for the operator and in all subsequent operations in the quarry or open pit.

**CMI Production** Basic instrument for angle measurement of rotation and

inclination

**Module Length** For measuring hole length and penetration rate.

There is also a length stop the drilling when preset length is

archived. Note that drill rig has to handle that signal.

**Module Logging** For communication with logging instrument

(For special orders, not incl. in this manual.)



The picture shows one CMI Production Rotation and Inclination angle measurement.

## 2 GENERAL DATA

Power supply 24V DC Power consumption 0,2A

Working temperature  $-20 - +50^{\circ} \text{ C}$ 

Environmental protection IP65

Angle measuring:

 $\begin{array}{ll} \mbox{Measurement range inclination} & \mbox{$\pm$} 60^{\rm o} \\ \mbox{Measurement range rotation} & \mbox{$360^{\rm o}$} \\ \mbox{Accuracy} & \mbox{$\pm$} 0.3 \mbox{$^{\rm o}$} \end{array}$ 

Hole length/penetration rate measuring:

Measurement range hole length  $0 - 99.9 \text{ m}, 0 - 99^{\circ} 11$ 

Measurement range penetration rate 0 - 9.99 m/min, 0 - 32' 7''/min

Accuracy length measurement  $\pm 1\%$ , min 0.05 m

#### **3 FUNCTION MASTER**

Upper display

Lower display

On/Off Switch

 $\Sigma$ m (total) button

Reset // button



+/- Knob

Absolute /Relative

Angle/Pause/Length mode

On/Off Switch. Turns the system On/Off.

 $\Sigma$ m (total) button. When pressed the total length (drilled in rock) is shown on the lower display. On the upper display the actual rate of penetration is shown.

To zero set press both Total ( $\Sigma m$ ) button and Reset (//) button at the same time.

Note: Angle/Pause/Length mode switch has to be in mode Length.

**Reset** // button. When pressed length measured for the last hole is zeroed. **Note** Angle/Pause/Length mode switch has to be in mode Length.

**Angle/Pause/Length mode.** If the switch is in Angle mode: the system shows angles. Lower display is rotation angle and upper display inclination angle. **Note:** All angles refer to the direction the sight is pointing. If checking angles while drilling, the system will continue to measure the length of the hole being drilled, while in Angle mode.

<u>If the switch is in Pause mode:</u> both displays will show '----'. **Note:** In this mode, the system will stop measuring length. Hence, if the driller wants to stop measuring length to avoid any hole length errors, e.g. during flushing a hole with percussion and assuming percussion is being used as a drilling signal, then this mode can be used.

<u>If the switch is in Length mode</u>: the system shows the rate of penetration on the upper display (updated every 3 seconds) and the position of the bit from the collar (or laser line) on the lower display.

#### Automatic system check.

The system has an automatic monitoring which checks that the master is communicating with all transducers in a proper way. If a cable is broken or if a transducer fails the upper display will show "Err" the lower display will show the node no which fails. If more than one node is failing the display will toggle between the faulty node numbers. If the master doesn't have contact with any transducer the display will show "OFF".

## 4. Mounting instructions.

#### Master

These shall be mounted in a protected place where the operator can reach and see them. The central unit shall be connected to a clean stable 24 V DC source. In most cases the rig's battery is the best choice.

The cable shall be protected by a fuse.

#### **Rotation transducer**

The rotation transducer shall be mounted in the transducer protection.

Mount the Transducer and Transducer protection for rotation angel measurement on the feeder holder on a place where it is well protected during drilling.

#### **Inclination transducer**

The Inclination transducer shall be mounted in the transducer protection.

Mount the Transducer and Transducer protection where it measures the inclination angel. I ex The tilt unit for the rotation.

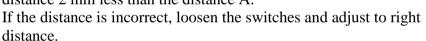
#### Length transducer

#### Standard length transducer:

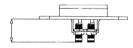
Mount the length transducer on the feeder on the opposite side to the drifter with the chain wheel pointing downwards in a place where it can link into the feeder chain.

## Rig-specific length transducer:

Measure the distance from the chain wheel to the cover's mounting plate (A). Check that the two proximity switches are placed at a distance 2 mm less than the distance A.



Do not tighten the nuts too much. Max torque 25 Nm (18 lb-ft).





#### Cylinder Feeder.

Contact Transtronic AB

#### **Cables**

The cables to the front transducers are protected by hydraulic hoses. Both ends of the hoses must be fixed with the supplied bracket which shall be welded near the transducer.

The hoses shall be placed together with the other hoses on the boom.

## 5 Checking of the system

## 5.1 Application program.

Make sure that the switch Angle/Pause/Length is in position Angle. (Left).

Turn the system off.

Press the reset // button down and hold it.

Turn the system on.

Release the reset // button.

Now the upper display shows 9999

Lower display shows 0

Press  $\Sigma$ m (total).

Upper Display Lower display 9001 3

Lower display shows the selected application.

3 = Production underground

If not contact Transtronic AB.

Press  $\Sigma$ m (total).

#### 5.2 Transducer nodes

Upper display shows transducer node number.

Lower display shows '1' if the transducer node is connected and '0' if not.

Press  $\Sigma$ m (total) to select next transducer node.

# Upper Display O1 Length transducer 1 = mounted 0 = not mounted Inclination transducer. 1 = mounted 0 = not mounted

Rotation transducer.  $\mathbf{1} = \text{mounted } \mathbf{0} = \text{not mounted}$ 

#### Mounted transducer's node shell be 1. All others shell be 0.

To change go to setting of the system. (Mounting instruction chapter 12).

Check that all connected transducers is in contact with the master.

## 5.3 Checking transducer directions.

Press  $\Sigma$ m (total) several times until the upper display shows 16.

Press  $\Sigma$ m (total).

Now the shows the values (after calibration) of the connected transducer.

If a transducer is not connected the system shows next transducer.

<b>Upper Display</b>	Lower display
1011	<b>Length transducer</b> counter. When the cradle is moved downwards the value shall increase.
1081	<b>Inclination transducer</b> When the feeder is vertical the shall be approx $0^0$ ( $\pm 3^0$ ). When the feeder is moved backwards the value shall be positive and when the feeder is moved to the forward the value shall be negative.
1111	<b>Rotation transducer</b> When the feeder is vertical the shall be approx $0^0$ ( $\pm 3^0$ ). When the feeder is moved to the right the value shall be positive and when the feeder is moved to the left the value shall be negative.

If any values count in the wrong direction go to setting of the system. (Chapter 12).

## **6.** Zero Setting

Adjust the feeder to vertical in both inclination and rotation,

Turn the system off. (Not necessary if you already are already in trouble shooting mode - then continue to press  $\Sigma m$  (total) until 2021 is shown.)

Press the reset // button down and hold it.

Turn the system on.

Release the // button.

Now the Upper display shows 9999

Lower display shows 0

Press  $\Sigma$ m (total) several times until the upper display shows 2021

For zero setting of a transducer press reset // button.

To select the next transducer press  $\Sigma$ m (total).

Upper dis	splay	Lower Display
2081	Inclination transducer.	0.0
2111	Rotation transducer.	0.0

## 7. Operator settings

Turn the system off. (Not necessary if you already are already in trouble shooting mode then continue to press  $\Sigma m$  (total) until 3101 is shown.)

Press the reset // button down and hold it.

Turn the system on.

Now the Upper display shows 9999

Lower display shows 0000

Press  $\Sigma$ m (total) several times until the upper display shows 3101

#### **Upper display**

## **Lower Display**

3101

Not in use

To save value press reset // button.

To change function press  $\Sigma m$  (total).

Drill rod length

**Upper display** 3102

**Lower Display** 

Shows the maximal rod length.

Press down the +/- knob and turn it so

it shows length of on drill rod.

0.0 is disconnection.

**Upper display** 

**Lower Display** 

3103

Shows the resolution in angle measurement.

Press down the +/- knob and turn to the resolution you want.

0.1, 0.2, 0.5 is the choice.

To save value press reset // button.

To change function press  $\Sigma m$  (total).

## 8. Test of Output Signals

Turn the system off. (Not necessary if you already are in trouble shooting mode then continue to press  $\Sigma$ m (total) until 3201 is shown)

Press the reset // button down and hold it.

Turn the system on.

Now the upper display shows 9999

Lower display shows 0000

Press  $\Sigma m$  (total) several times until the upper display shows 3201

**Upper display** Lower Display

3201 Shows nothing. When pressing // button the output signal becomes active

(lower display will show '1'.

## 9. Test of Input Signals

Turn the system off. (Not necessary if you already are in trouble shooting mode then continue to press  $\Sigma$ m (total). until 3301 is shown)

Press the reset // button down and hold it.

Turn the system on.

Now the upper display shows 9999

Lower display shows 0000

Press  $\Sigma$ m (total) several times until the upper display shows 3301

## Upper display Lower display

3301 Shows 0000. If an input gets active it changes to 1

Drilling signal 4	Drilling signal 3	Drilling signal 2	Drilling signal 1	Lower Display
0	0	0	1	0001
0	0	1	0	0010
0	1	0	0	0100
1	0	0	0	1000

#### **Upper display** Lower display

3401 Shows 0 when the switch Absolute /Relative is in position Absolute.

Shows 1 when the switch Absolute /Relative is in position Relative

Shows 0 when the switch Angle/Pause/Length is in position Angle.

Shows 1 when the switch Angle/Pause/Length is in position Pause.

Shows 2 when the switch Angle/Pause/Length is in position Length.

# 10. Troubleshooting angle system Fault Action

If a cable is broken or if a transducer fails the upper display will show "Err" the lower display will show the node no which fails. If more than one node is failing the display will toggle between the faulty node numbers.

If the master doesn't have contact with any transducer the display will show "OFF".

The displays shows nothing. And the lights in the displays are off. Check power supply to the master. Should be between 22 and 28V DC.

(Input voltage)

If no voltage check the fuse.

Display for inclination or rotation unstable or shows incorrect value.

Run the trouble shooting mode and try to locate the faulty transducer. (See chapter 7.3)

Connect a spare (lose) cable to the faulty transducer. If system now functions OK, change the signal cable

If not change the transducer.

If the measurement still doesn't work correct, change the master.

## 11. Troubleshooting length system

**Fault** Action

fault. See chapter 7.3 (Upper Display 1011).

Missing signal from the length transducer. Check the wire on the length transducer.

Check that the proximity switches in the length transducer is ok by measuring voltage inside the connection box on the feeder (if chain feeder used).

See drawing 06090830

If no drilling signals

Trouble shoot the control signal connections in the

Electrical cabinet. See drawing 06090830

## 12 Setting of the system

Here you tell the system witch transducer that is connected:

Turn the system off.

Press the reset // button down and hold it.

Turn the system on.

Release the // reset button.

Now the Upper display shows 9999

Lower display shows 0

Press down +/- knob and adjust so that you have 0099 on the lower display.

Press  $\Sigma$ m (total).

If you what to change press down +/- knob and adjust to 0 or 1.

To save it press // reset button.

Go to next press  $\Sigma m$  (total).

Function	<b>Upper Display</b>	<b>Lower Display</b>
Length Transducer Connected Not connected	01	1 0
Press $\Sigma$ m (total).		
Inclination transducer Connected Not connected	08	1 0
Press Σm (total).  Rotation transducer Connected Not connected	11	1 0
Press $\Sigma$ m (total).		

Press  $\Sigma$ m (total) until 1011 on the upper display. Or the first connected transducer.

Length transducer direction Normal Reversed direction	1011	0* ('*' is default) 1
Inclination transducer direction Normal Reversed direction	1081	0* 1
Rotation transducer direction Normal Reversed direction	1111	0* 1

Press  $\Sigma m$  (total) until 5001 on the upper display. Or the first connected transducer.

Chain selection for the length transducer 5002 cylinder feeder 1:2 cylinder feeder 1:1 1" 1 1/4" 1 1/2" 1 3/4" 2" 1 "Wire Setting of measurement distance (mm)/pulse To change to 10 of mm press $\Sigma$ m. Press // to save value in the length transducer 5002	1* 2 3 4 5 6 7 8 0 nsducer.
Drilling signals connection 5003	
Only one drilling signal (e.g. percussion or rod handling)  Drill 1 Drill 2  0 x Length measurement off  1 x Length measurement on  The normal way to Digital 1 is to mount a relay over the hour counter for the drill hammer.  Both drilling signal 1 and 2 (Normally drilling rotation and air on)  Drill 1 Drill 2  0 0 Length measurement off  1 1 Length measurement on  To get in to length measurement, both signals  Must be active.  To get out of length measurement mode both signals must be inactive.	1*
Not used:	3
Hole length or hole depth Hole length Hole depth	0* 1
Type of length measurement mode Length of the hole (Shows the length of the drilled hole). Position of the bit. (The system keeps a steady check of the position of bit).	0 1*

Hammer type on rig

5006

Top Hammer 0\*
ITH hammer 1

If ITH hammer selected the system will show distance from hole bottom on the upper display and the position of the bit on the lower display when the rod from extracted in the hole.

Measurement units 5007

Metric 0\*
US 1

When using metric units the system shows hole length and total length in metres, penetration rate in metres/minute.

With using US units the system shows hole length and total length in feet and inches, penetration rate in feet and inches/minute.

By pressing  $\Sigma m$  (total) again the system will go to the start of the setup program again with 0099 on the lower display. This is useful for checking the setup. If not, shut the system off

Not used 5008

## 15 Checking and setting summary

Chec No co	<del>-</del>	Setup Code 99	)
	Application Selected application program		
2 3 4	Check of node	8	Node on/off Length transducer Node on/off Inclination transducer Node on/off Rotation transducer
1000	Measurement values	1000	Direction node
	Length transducer	1011	Direction length transducer
	Not used	4004	
	Inclination transducer Rotation transducer		Direction Inclination transducer Direction Rotation Transducer
2081	Zero setting Zero setting Inclination transducer Zero setting Rotation transducer		
3100	Operator settings		
	Not used		
	Setting of rod length		
3103	Measurement resolution		
	Output signals Test of stop signal		
3301 3401	Input signals Check of drilling signals Check of switch Absolute/Relative		
3501	Check of switch Angle/Pause/Lengt	5000	System settings
		5002 5003 5004 5005 5006 5007	Selection of length transducer  No of drilling signals  Hole length/hole depth 0=length 1=depth  Hole length/bit pos 0=hole length 1=pos bit  Hammer 0=top 1=ITH  Units 0=m 1=US  GPS Compass Bench drilling

